# IMPROVED JOINT MONITORING OF MEAN AND VARIANCE WITH AN APPLICATION TO PRODUCTION DATA 

Seher Malik ${ }^{1}$ and Muhammad Hanif ${ }^{2}$<br>Department of Statistics<br>National College of Business Administration and Economics<br>Lahore, Pakistan<br>Email: ${ }^{1}$ seharmalik28@gmail.com<br>${ }^{2}$ drmianhanif@gmail.com


#### Abstract

This study focuses on the application of Statistical Process Control (SPC) techniques to detect shifts in the production process. The use of control charts as an effective means for monitoring these shifts, we introduce a novel control chart based on the Max Extended Exponentially Weighted Moving Average (MxEEWMA) statistic. The proposed chart is designed for simultaneous monitoring of mean and variance shifts in the production process. An extensive numerical evaluation of the chart's performance is conducted, employing Average Run Lengths (ARLs) and Standard Deviation of Run Lengths (SDRLs) through Monte Carlo simulation. The comparative analyses are carried out between the Max EEWMA control chart and existing Max EWMA control charts. Furthermore, the practical applicability of the proposed control chart is illustrated using a real-world dataset.


## KEYWORDS

EWMA, EEWMA Statistics, Max-EEWMA Control Chart, Joint Monitoring.

## 1. INTRODUCTION

Statistical quality control describes the application of statistical techniques in observing and maintaining the quality of goods and services. Statistical quality control, commonly referred as SPC, is a procedure for monitoring and evaluating the process through statistical study. It uses a statistical technique to evaluate and investigate the differences in process production. Most often, it is used in manufacturing processes to monitor process quality and maintain processes. Regardless of the quality of the design, it can guarantee that the product or service is produced as planned and designed. SPC may be used to sustain the reliability of how goods is produced, however, it will not improve consistency of poorly designed products. Hence, products are manufactured according to designed reliability.

In the 1920s, Walter A. Shewhart, renowned inventor of control charts, presented the idea of control charts to sustain the product's quality. He developed many control charts like R and S , which are based on information from the last observation and samples collected from the production process rather than past data. Later, (Roberts, 1959) and (Page, 1954) established the exponentially weighted moving average (EWMA) chart and cumulative sum (CUSUM) chart, which are more sensitive to monitoring small and moderate shifts in comparison to the preceding charts. Xie (1999) and Chen et al. (2001)
proposed the idea of combined supervising of both parameters mean shift as well as variance shift with a single control chart and named it the Maximum EWMA (MaxEWMA) control chart. Ostadsharif Memar and Niaki (2011) presented a new scheme of EWMA control charts to monitor both mean and variance concurrently by using a single statistic to overcome the difficulties in existing charts of monitoring both measurements by using two distinct charts. The simulation study of the proposed chart with other present different combinations of charts shows significantly better performance in monitoring both measurements simultaneously. Khoo et al. (2010) proposed a double EWMA control chart (Max-DEWMA) as an expansion of single Max-EWMA charts that significantly perform better in detecting both moderate and smaller shifts simultaneously in mean and variance. Naveed et al. (2018) established a generalized memory type control chart known as the Extended EWMA control chart to detect the small shifts, which is based on both past and current information from variables of interest with their past information and weights of EEWMA statistics. The proposed control chart efficiently detects the smaller shift as compared to other charts. (Noor-ul-Amin et al., 2019) suggested a new control chart for joint observing under pair ranked set sampling with likelihood ratio test. It was concluded that the recommended chart is efficient in identifying variance and mean shifts individually as well as jointly. Javaid et al. (2020) recommended a Max-EWMA control chart to analyze the influence of measurement errors on joint examining of mean and variance. The Covariate model technique, along with Max-EWMA, was worked to analyze the influence of measurement error and multiple measurements on the monitoring process. Measurement errors have a negative impact on Max-EWMA control chart efficiency, and it can be enhanced by taking multiple measurements of quality characteristics to identify smaller shifts during the monitoring process. (Karoon et al., 2022) presented a new idea of using the EEWMA control chart for exponential white noise with a first-order autoregressive (AR (1)) process. The implementation of the developed control chart was estimated through the application of real-life data of 24-hour absorption of PM10 (particulate matter) in polluted air, which is a major cause of the environmental problem of air pollution. Real life applications reveal that the suggested control chart outperforms the EWMA chart under several circumstances.(Chatterjee et al., 2022) developed a new TEWMA-Max (Triple EWMA-Max) control chart for combined examining of procedure mean and variability. (Engmann \& Han, 2022) proposed a new method of multi-chart with EWMA and CUSUM for simultaneous detection of mean and variability during procedure.(Riaz et al., 2022) evaluate the measurement error effect on the implementation of combined monitoring of mean and coefficient of variation. The rest of the article is structured as, In Section 2, we evaluate the existing Max-EWMA chart for joint monitoring. In section 3, we explained the proposed Max-EEWMA control chart for simultaneously monitoring. To evaluate the performance of the proposed chart, a simulation study is explained in section 4. In section 5, a real-life case is presented to illustrate the suggested chart in a real-life application. The main findings are given in section 6, and the conclusion is presented in the concluding section.

## 2. MAX-EWMA CONTROL CHART FOR JOINT MONITORING

The existing Shewhart control chart utilizes entire available information in the present sample, but the EWMA control chart was developed in a way that most weights was provided to the latest subgroup and all preceding observations were given geometrically
decreasing weights. The EWMA statistics are used to examine only the process production mean shift. Roberts (1959) proposed new EWMA statistics for the $i^{\text {th }}$ sample of size 5 for monitoring only one parameter.

$$
\begin{equation*}
Z_{i}=\lambda \bar{Y}_{i}+(1-\lambda) Z_{i-1} \tag{1}
\end{equation*}
$$

Xie (1999) and Chen et al. (2001) proposed an idea of combined observing of both parameters mean shift as well as variance shift with single control chart and known as it Maximum EWMA (Max-EWMA) control chart. If $Y$ is normally distributed random variable of interest in process production with $\mu=\mu_{0}+a \sigma_{0}$ mean and $\sigma^{2}=b^{2} \sigma_{0}^{2}$ variance, where $\mu_{0}$ and $\sigma_{0}^{2}$ are well-known parameters for variance and mean, respectively. The $b$ and $a$ are shifts in variance and mean, having 1 and 0 values for an in-control procedure, respectively. The Max-EWMA statistics can detect smaller shifts more efficiently. The transformed normally distributed statistics of mean and variance for in-control procedures with zero mean and unity variance for $i^{t h}$ sample are

$$
\begin{align*}
U_{i} & =\frac{\bar{Y}_{i}-\mu_{0}}{\sqrt{\sigma_{0}^{2} / n}}  \tag{2}\\
V_{i} & =\emptyset^{-1}\left[H\left\{\frac{(n-1) S_{i}^{2}}{\sigma_{0}^{2}},(n-1)\right\}\right] \tag{3}
\end{align*}
$$

where $i=1,2,3, \ldots, n$ is size of $i^{\text {th }}$ sample, the mean $\bar{Y}_{i}=\frac{\sum_{i=1}^{n} Y_{i j}}{n}$ of $i^{\text {th }}$ sample, and variance $S_{i}^{2}=\frac{\sum_{i=1}^{n}\left(Y_{i j}-\bar{Y}_{i}\right)^{2}}{n-1}$ of $i^{\text {th }}$ sample, $\emptyset^{-1}$ is the inverse function of standard normal distribution, while $H(\xi, v)$ follow $\chi^{2}$ distribution with $v$ degree of freedom.

By using equations (2) and (3), the two EWMA statistics are as follows

$$
\begin{align*}
& P_{i}=\lambda U_{i}+(1-\lambda) U_{i-1}  \tag{4}\\
& Q_{i}=\lambda V_{i}+(1-\lambda) V_{i-1} \tag{5}
\end{align*}
$$

where $P_{0}=Q_{0}=0$ for first sample and $\lambda$ is smoothing constant, such that $0<\lambda \leq 1$.
In proposed statistics the total of weights is unity. The quantities $U_{i-1}$ and $V_{i-1}$ denotes the variable's preceding value. We will use just one maximum absolute statistic for joint examining of mean and variance, instead of both statistics separately.

$$
\begin{equation*}
\operatorname{Max}-\text { EWMA }=\operatorname{Max}\left(\left|P_{i}\right|,\left|Q_{i}\right|\right) \tag{6}
\end{equation*}
$$

Only one upper control limit $(U C L)$ is adequate for plotting Max-EEWMA statistics for controlling production procedure.

$$
\begin{equation*}
U C L=(1.128379+0.602810 \times L) \sqrt{\operatorname{Var}\left(P_{j}\right)} \tag{7}
\end{equation*}
$$

where $L$ is control constant and for in control process it is calculated to attain the required average run length, which is denoted by $\mathrm{ARL}_{0}$, and variance is $\operatorname{Var}\left(P_{j}\right)=\operatorname{Var}\left(Q_{j}\right)=\sqrt{\frac{\lambda}{(2-\lambda)}}$.

## 3. PROPOSED MAX-EEWMA CONTROL CHART FOR JOINT MONITORING

In this part, the suggested Max-EEWMA control chart is established. We assumed that the quality characteristics $U_{i}$ and $V_{i}$ follows normal distribution. We proposed the Max- extended EWMA control chart by combining equation 4 and 5 with extended EWMA statistics proposed by (Naveed et al., 2018). Note that a critique paper is presented by Haq and Woodal (2023) on the modified EWMA versions and they specifically discussed the EEWMA version. The Khan et al. (2023) presented a rebuttal paper on the use of EEWMA statistic. The reader may consult these papers for further clarity. The design of the proposed control chart is given by:

Step 1: Choose a sample of " $n$ " size. Calculate the two proposed EEWMA statistics.
The two proposed EEWMA statistics for mean and variance are

$$
\begin{align*}
& P_{i}=\psi_{1} U_{i}-\psi_{2} U_{i-1}+\left(1-\psi_{1}+\psi_{2}\right) P_{i-1}  \tag{8}\\
& Q_{i}=\psi_{1} V_{i}-\psi_{2} V_{i-1}+\left(1-\psi_{1}+\psi_{2}\right) Q_{i-1} \tag{9}
\end{align*}
$$

where $P_{0}=Q_{0}=0$ for first sample and $0<\psi_{1} \leq 1$ and $0 \leq \psi_{2}<\psi_{1}$.
In proposed statistics the total weight is one. The quantities $U_{i-1}$ and $V_{i-1}$ denotes the variable's preceding value and $P_{i-1}$ and $Q_{i-1}$ signifies the statistics preceding values.

For in-control, the mean and variance of EEWMA statistics are

$$
\begin{align*}
& E\left(P_{j}\right)=E\left(Q_{j}\right)=\mu  \tag{10}\\
& \operatorname{Var}\left(P_{j}\right)=\operatorname{Var}\left(Q_{j}\right)  \tag{11}\\
& \operatorname{Var}\left(P_{j}\right)=\sigma^{2}\left[\left(\psi_{1}^{2}+\psi_{2}^{2}\right)\left\{\frac{1-a^{2 i}}{2\left(\psi_{1}-\psi_{2}\right)-\left(\psi_{1}-\psi_{2}\right)^{2}}\right\}\right. \\
& \left.\quad-2 a \psi_{1} \psi_{2}\left\{\frac{1-a^{2 i-2}}{2\left(\psi_{1}-\psi_{2}\right)-\left(\psi_{1}-\psi_{2}\right)^{2}}\right\}\right] \tag{12}
\end{align*}
$$

We will use only a single maximum absolute statistic for joint examining of mean and variance instead of both statistics separately.

Step 2: Choose the Max statistics from among two of proposed EEWMA statistics.

$$
\begin{equation*}
\text { Max-EEWMA }=\operatorname{Max}\left(\left|P_{i}\right|,\left|Q_{i}\right|\right), \tag{13}
\end{equation*}
$$

where $i=1,2,3, \ldots$ Max-EEWMA statistics is maximum statistic out of two absolute statistics for mean and variance.

According to (Xie, 1999) by using absolute values only upper control limit (UCL) is adequate for plotting Max-EEWMA statistics for controlling production procedure.

Step 3: The process will be declared in-control when the proposed EEWMA statistic is beyond the limit otherwise it is out-of-control. The upper control limit is expressed by " $U C L$ ".

$$
\begin{equation*}
U C L=(1.128379+0.602810 \times L) \sqrt{\operatorname{Var}\left(P_{j}\right)} \tag{14}
\end{equation*}
$$

where $L$ is control constant and for in control process it is calculated to attain the required average run length, which is denoted by $\operatorname{ARL}_{0}$, and variance is $\operatorname{Var}\left(P_{j}\right)=\operatorname{Var}\left(Q_{j}\right)$ for large repetitive samples when both $P_{j}$ and $Q_{j}$ follow the standard normal distribution.

## 4. SIMULATION STUDY

In this segment the suggested chart is evaluated by an extensive study for this purpose the statistic is generating from normal distribution such that $U_{i} \sim N(0,1)$ and $V_{i} \sim N(0,1)$. Algorithm for calculating ARL and SDRL for Max-EEWMA is given below:

Step 1: Control statistics for sample variance and mean.
i. For the in-control process, generate 30000 random samples of " $n$ " size from normal distribution.
ii. Compute the proposed statistic for every sample.

Step 2: Establishing Control limits.
i. Choose the initial values of two parameters $L$ and $\lambda$.
ii. Calculate the statistic for both mean and variance.
iii. Determine the transformed statistic for mean and variance to attain Max-EEWMA statistics (Haq, 2017).
iv. Evaluate the proposed statistic for out-of-control signal. When procedure is declared as in-control, then proceed to step v, Else record samples number as run length for in-control.
v. Replicate steps from II to IV 30000 times to evaluate $A R L_{0}$. If we attain the required $A R L_{0}$ then go to step 3 with existing $\lambda$ value. Otherwise, change value of $\lambda$ and repeat steps II to V of step-2.

Step 3: Calculating the ARL for out-of-control
i. Generate a random variable $Y$ from normal distribution at each sample by considering a mean shift, i.e. $Y \sim N(\delta, 1)$.
ii. Evaluate the proposed statistic for the sample.
iii. Steps I and II from step 3 will repeat till the procedure is considered as out-ofcontrol. The number of samples will be recorded as a run-length.
iv. The entire procedure will be repeated 10,000 times to evaluate values of $A R L$ and SDRL.
v. Compute upper control limit and compare the $U C L$ and Max-EEWMA statistics. The process will be in control if Max-EEWMA remain under the $U C L$. After that, generate another sample and repeat steps I to IV.
vi. The procedure has been shifted to be out of control if Max-EEWMA statistic is outside $U C L$ limit, and the production procedure will stop, and the required run length will be achieved.

We have utilized 30,000 replicates to compute every $A R L$ and $S D R L$. We arrived at $L=2.278$ to attain $A R L_{0}=370$ for $\psi_{1}=0.15$ and $\psi_{2}=0.03$. Several combinations for mean shift i.e., $a=0.0,0.1,0.25,0.50,0.75,1,1.5,2.0$ and for variance shift i.e.,
$b=0.25,0.50,0.75,0.90,1.00,1.10,1.25,1.50,2.00,2.50,3.00$ are used in this study. We can observe from Table 1 that Max-EEWMA chart can efficiently detect procedure mean and variance shifts simultaneously. It can be easily observed that ARLs decay as mean shift increases and, similarly, ARLs decrease with the increase in variance shift as well, which indicates the capability of detecting both shifts at an early stage.

Table 1
ARLs and SDRLs of Max-EEWMA Chart and Max-EWMA Chart for $\psi_{1}=\lambda=0.154$

| Shifts |  | $\begin{aligned} & \psi_{2}=\mathbf{0 . 0 3} \\ & \boldsymbol{L}=2.278 \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=\mathbf{0 . 0 5} \\ & \boldsymbol{L}=\mathbf{1 . 6 2 8} \\ & \hline \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=\mathbf{0 . 0 7} \\ & \boldsymbol{L}=\mathbf{0 . 9 8 4} \end{aligned}$ |  | $\begin{gathered} \lambda=0.15 \\ L=3.168 \end{gathered}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $b$ | $a$ | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL |
| 0.25 | 0.00 | 1.536 | 0.581 | 1.259 | 0.475 | 1.082 | 0.285 | 3.034 | 0.444 |
|  | 0.10 | 1.528 | 0.581 | 1.258 | 0.474 | 1.083 | 0.288 | 3.034 | 0.448 |
|  | 0.25 | 1.529 | 0.584 | 1.261 | 0.477 | 1.084 | 0.289 | 3.034 | 0.442 |
|  | 0.50 | 1.533 | 0.582 | 1.260 | 0.476 | 1.081 | 0.286 | 3.032 | 0.448 |
|  | 0.75 | 1.535 | 0.583 | 1.251 | 0.467 | 1.067 | 0.256 | 3.032 | 0.443 |
|  | 1.00 | 1.441 | 0.508 | 1.114 | 0.320 | 1.007 | 0.083 | 2.978 | 0.37 |
|  | 1.50 | 1.000 | 0.016 | 1.000 | 0.000 | 1.000 | 0.000 | 2.084 | 0.278 |
|  | 2.00 | 1.000 | 0.000 | 1.000 | 0.000 | 1.000 | 0.000 | 2.000 | 0.000 |
| 0.50 | 0.00 | 4.381 | 2.108 | 3.913 | 2.203 | 3.264 | 2.224 | 5.882 | 1.688 |
|  | 0.10 | 4.356 | 2.080 | 3.894 | 2.205 | 3.218 | 2.215 | 5.892 | 1.693 |
|  | 0.25 | 4.371 | 2.084 | 3.905 | 2.193 | 3.244 | 2.238 | 5.878 | 1.684 |
|  | 0.50 | 4.165 | 1.864 | 3.670 | 1.991 | 2.897 | 1.966 | 5.725 | 1.484 |
|  | 0.75 | 3.016 | 1.201 | 2.502 | 1.270 | 1.864 | 1.128 | 4.667 | 0.874 |
|  | 1.00 | 1.978 | 0.774 | 1.522 | 0.705 | 1.218 | 0.503 | 3.52 | 0.585 |
|  | 1.50 | 1.051 | 0.220 | 1.009 | 0.097 | 1.001 | 0.035 | 2.249 | 0.432 |
|  | 2.00 | 1.000 | 0.005 | 1.000 | 0.000 | 1.000 | 0.000 | 1.995 | 0.067 |
| 0.75 | 0.00 | 20.686 | 14.521 | 19.213 | 13.888 | 17.274 | 13.404 | 23.942 | 16.262 |
|  | 0.10 | 20.587 | 14.542 | 18.950 | 13.585 | 17.334 | 13.772 | 23.742 | 16.217 |
|  | 0.25 | 17.128 | 11.146 | 15.757 | 10.771 | 13.956 | 10.831 | 20 | 12.194 |
|  | 0.50 | 7.210 | 3.866 | 6.470 | 4.039 | 5.387 | 4.154 | 8.944 | 3.463 |
|  | 0.75 | 3.463 | 1.793 | 2.956 | 1.801 | 2.374 | 1.687 | 5.116 | 1.441 |
|  | 1.00 | 2.070 | 1.023 | 1.739 | 0.960 | 1.449 | 0.803 | 3.614 | 0.833 |
|  | 1.50 | 1.144 | 0.366 | 1.066 | 0.258 | 1.022 | 0.153 | 2.333 | 0.485 |
|  | 2.00 | 1.005 | 0.072 | 1.001 | 0.035 | 1.000 | 0.015 | 1.963 | 0.211 |
| 0.90 | 0.00 | 151.393 | 147.460 | 138.618 | 137.888 | 122.703 | 129.558 | 171.722 | 162.445 |
|  | 0.10 | 110.456 | 106.430 | 99.204 | 97.557 | 89.191 | 93.411 | 127.085 | 117.567 |
|  | 0.25 | 29.201 | 23.424 | 26.620 | 21.914 | 23.227 | 20.978 | 34.504 | 26.3 |
|  | 0.50 | 7.368 | 4.639 | 6.681 | 4.771 | 5.616 | 4.750 | 9.287 | 4.283 |
|  | 0.75 | 3.488 | 2.023 | 2.998 | 2.008 | 2.496 | 1.890 | 5.172 | 1.725 |
|  | 1.00 | 2.100 | 1.140 | 1.826 | 1.079 | 1.530 | 0.924 | 3.632 | 0.994 |
|  | 1.50 | 1.197 | 0.437 | 1.110 | 0.338 | 1.049 | 0.233 | 2.375 | 0.526 |
|  | 2.00 | 1.016 | 0.126 | 1.005 | 0.074 | 1.002 | 0.044 | 1.942 | 0.294 |
| 1.00 | 0.00 | 371.998 | 386.464 | 370.102 | 402.895 | 370.918 | 447.495 | 373.574 | 369.346 |
|  | 0.10 | 144.198 | 144.138 | 132.407 | 139.297 | 118.257 | 137.058 | 158.957 | 150.107 |
|  | 0.25 | 27.580 | 23.214 | 24.830 | 22.382 | 21.379 | 21.309 | 32.336 | 25.219 |
|  | 0.50 | 7.139 | 4.832 | 6.408 | 4.914 | 5.341 | 4.832 | 9.213 | 4.565 |
|  | 0.75 | 3.464 | 2.144 | 3.007 | 2.128 | 2.505 | 1.988 | 5.196 | 1.887 |
|  | 1.00 | 2.138 | 1.217 | 1.850 | 1.141 | 1.582 | 0.997 | 3.668 | 1.096 |
|  | 1.50 | 1.234 | 0.486 | 1.141 | 0.396 | 1.076 | 0.296 | 2.387 | 0.564 |
|  | 2.00 | 1.025 | 0.158 | 1.011 | 0.107 | 1.005 | 0.073 | 1.928 | 0.348 |


| Shifts |  | $\begin{aligned} & \psi_{2}=\mathbf{0 . 0 3} \\ & L=2.278 \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=\mathbf{0 . 0 5} \\ & \boldsymbol{L}=\mathbf{1 . 6 2 8} \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=\mathbf{0 . 0 7} \\ & \boldsymbol{L}=\mathbf{0 . 9 8 4} \end{aligned}$ |  | $\begin{gathered} \lambda=0.15 \\ L=3.168 \end{gathered}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $b$ | $a$ | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL |
| 1.10 | 0.00 | 77.946 | 78.310 | 71.205 | 76.808 | 61.025 | 74.903 | 88.954 | 83.21 |
|  | 0.10 | 55.939 | 55.130 | 50.578 | 53.464 | 42.559 | 50.720 | 64.791 | 58.352 |
|  | 0.25 | 21.069 | 18.277 | 18.777 | 17.659 | 15.513 | 16.881 | 25.574 | 19.328 |
|  | 0.50 | 6.736 | 4.954 | 5.927 | 4.868 | 4.857 | 4.670 | 8.994 | 4.673 |
|  | 0.75 | 3.422 | 2.269 | 2.941 | 2.187 | 2.422 | 1.981 | 5.181 | 2.024 |
|  | 1.00 | 2.145 | 1.285 | 1.871 | 1.205 | 1.601 | 1.035 | 3.688 | 1.189 |
|  | 1.50 | 1.268 | 0.529 | 1.165 | 0.428 | 1.098 | 0.345 | 2.41 | 0.598 |
|  | 2.00 | 1.039 | 0.197 | 1.020 | 0.145 | 1.009 | 0.096 | 1.92 | 0.392 |
| 1.25 | 0.00 | 15.417 | 14.031 | 13.481 | 13.717 | 10.822 | 12.653 | 19.829 | 14.413 |
|  | 0.10 | 14.515 | 13.035 | 12.507 | 12.431 | 9.993 | 11.787 | 18.587 | 13.22 |
|  | 0.25 | 10.573 | 9.135 | 9.236 | 8.961 | 7.382 | 8.523 | 14.207 | 9.238 |
|  | 0.50 | 5.435 | 4.291 | 4.704 | 4.189 | 3.749 | 3.803 | 8.043 | 4.134 |
|  | 0.75 | 3.151 | 2.260 | 2.746 | 2.161 | 2.236 | 1.897 | 5.081 | 2.12 |
|  | 1.00 | 2.112 | 1.342 | 1.858 | 1.249 | 1.581 | 1.050 | 3.68 | 1.304 |
|  | 1.50 | 1.296 | 0.577 | 1.196 | 0.489 | 1.120 | 0.383 | 2.427 | 0.665 |
|  | 2.00 | 1.061 | 0.249 | 1.033 | 0.185 | 1.016 | 0.131 | 1.912 | 0.455 |
| 1.50 | 0.00 | 4.711 | 4.005 | 3.935 | 3.751 | 3.103 | 3.252 | 7.309 | 3.949 |
|  | 0.10 | 4.570 | 3.895 | 3.876 | 3.671 | 3.035 | 3.241 | 7.188 | 3.836 |
|  | 0.25 | 4.236 | 3.558 | 3.557 | 3.339 | 2.798 | 2.868 | 6.815 | 3.512 |
|  | 0.50 | 3.337 | 2.673 | 2.799 | 2.446 | 2.271 | 2.107 | 5.637 | 2.638 |
|  | 0.75 | 2.500 | 1.843 | 2.131 | 1.649 | 1.773 | 1.369 | 4.441 | 1.856 |
|  | 1.00 | 1.915 | 1.258 | 1.680 | 1.125 | 1.473 | 0.950 | 3.505 | 1.318 |
|  | 1.50 | 1.316 | 0.520 | 1.217 | 0.533 | 1.139 | 0.432 | 2.446 | 0.763 |
|  | 2.00 | 1.088 | 0.306 | 1.055 | 0.245 | 1.030 | 0.183 | 1.91 | 0.546 |
| 2.00 | 0.00 | 1.814 | 1.234 | 1.601 | 1.077 | 1.400 | 0.863 | 3.406 | 1.44 |
|  | 0.10 | 1.817 | 1.239 | 1.598 | 1.082 | 1.393 | 0.842 | 3.395 | 1.429 |
|  | 0.25 | 1.779 | 1.194 | 1.579 | 1.044 | 1.391 | 0.845 | 3.338 | 1.397 |
|  | 0.50 | 1.704 | 1.111 | 1.504 | 0.936 | 1.345 | 0.771 | 3.215 | 1.309 |
|  | 0.75 | 1.570 | 0.972 | 1.411 | 0.821 | 1.275 | 0.661 | 2.992 | 1.193 |
|  | 1.00 | 1.435 | 0.802 | 1.317 | 0.692 | 1.216 | 0.560 | 2.75 | 1.046 |
|  | 1.50 | 1.247 | 2.930 | 1.168 | 0.465 | 1.105 | 0.366 | 2.254 | 0.804 |
|  | 2.00 | 1.105 | 0.328 | 1.071 | 0.279 | 1.043 | 0.428 | 1.857 | 0.64 |
| 2.50 | 0.00 | 1.303 | 0.635 | 1.217 | 0.544 | 1.143 | 0.429 | 2.352 | 0.93 |
|  | 0.10 | 1.307 | 0.644 | 1.219 | 0.543 | 1.144 | 0.434 | 2.357 | 0.932 |
|  | 0.25 | 1.293 | 0.626 | 1.206 | 0.524 | 1.138 | 0.421 | 2.349 | 0.92 |
|  | 0.50 | 1.276 | 0.600 | 1.196 | 0.506 | 1.129 | 0.407 | 2.295 | 0.901 |
|  | 0.75 | 1.251 | 0.570 | 1.170 | 0.465 | 1.117 | 0.389 | 2.227 | 0.871 |
|  | 1.00 | 1.209 | 0.511 | 1.148 | 0.429 | 1.101 | 0.352 | 2.134 | 0.817 |
|  | 1.50 | 1.132 | 0.396 | 1.093 | 0.330 | 1.062 | 0.269 | 1.927 | 0.729 |
|  | 2.00 | 1.080 | 0.300 | 1.060 | 1.222 | 1.054 | 2.422 | 1.704 | 0.64 |
| 3.00 | 0.00 | 1.134 | 0.394 | 1.092 | 0.323 | 1.064 | 0.270 | 1.859 | 0.741 |
|  | 0.10 | 1.137 | 0.399 | 1.094 | 0.333 | 1.061 | 0.259 | 1.854 | 0.731 |
|  | 0.25 | 1.136 | 0.396 | 1.093 | 0.330 | 1.062 | 0.266 | 1.857 | 0.74 |
|  | 0.50 | 1.128 | 0.384 | 1.091 | 0.324 | 1.056 | 0.251 | 1.828 | 0.728 |
|  | 0.75 | 1.121 | 0.372 | 1.081 | 0.303 | 1.054 | 0.250 | 1.799 | 0.719 |
|  | 1.00 | 1.107 | 0.350 | 1.075 | 0.294 | 1.048 | 0.231 | 1.759 | 0.694 |
|  | 1.50 | 1.079 | 0.295 | 1.056 | 0.253 | 1.036 | 0.198 | 1.646 | 0.649 |
|  | 2.00 | 1.052 | 0.234 | 1.036 | 0.196 | 1.024 | 0.218 | 1.521 | 0.594 |

Table 2
ARLs and SDRLs of Max-EEWMA Chart and Max-EWMA Chart for $\psi_{1}=\lambda=0.2$

| Shifts |  | $\begin{aligned} & \psi_{2}=0.03 \\ & \mathrm{~L}=2.630 \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=0.05 \\ & \mathrm{~L}=2.167 \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=0.07 \\ & \mathrm{~L}=1.688 \end{aligned}$ |  | $\begin{gathered} \boldsymbol{\psi}_{2}=\mathbf{0 . 1} \\ \mathrm{L}=0.977 \end{gathered}$ |  | $\begin{gathered} \lambda=0.2 \\ \mathrm{~L}=3.250 \end{gathered}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $b$ | $a$ | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL |
| 0.25 | 0.00 | 1.718 | 0.613 | 1.505 | 0.594 | 1.297 | 0.510 | 1.091 | 0.301 | 2.817 | 0.495 |
|  | 0.10 | 1.721 | 0.609 | 1.504 | 0.589 | 1.297 | 0.506 | 1.093 | 0.301 | 2.823 | 0.488 |
|  | 0.25 | 1.716 | 0.611 | 1.511 | 0.595 | 1.297 | 0.507 | 1.088 | 0.297 | 2.820 | 0.495 |
|  | 0.50 | 1.727 | 0.613 | 1.505 | 0.598 | 1.298 | 0.509 | 1.090 | 0.301 | 2.819 | 0.493 |
|  | 0.75 | 1.724 | 0.613 | 1.506 | 0.598 | 1.297 | 0.511 | 1.073 | 0.275 | 2.817 | 0.497 |
|  | 1.00 | 1.648 | 0.526 | 1.400 | 0.509 | 1.154 | 0.366 | 1.008 | 0.091 | 2.779 | 0.437 |
|  | 1.50 | 1.005 | 0.072 | 1.000 | 0.011 | 1.000 | 0.000 | 1.000 | 0.000 | 2.002 | 0.047 |
|  | 2.00 | 1.000 | 0.000 | 1.000 | 0.000 | 1.000 | 0.000 | 1.000 | 0.000 | 1.997 | 0.059 |
| 0.50 | 0.00 | 4.828 | 2.221 | 4.568 | 2.304 | 4.202 | 2.397 | 3.460 | 2.480 | 5.781 | 1.920 |
|  | 0.10 | 4.798 | 2.200 | 4.564 | 2.301 | 4.213 | 2.389 | 3.436 | 2.456 | 5.779 | 1.945 |
|  | 0.25 | 4.800 | 2.227 | 4.554 | 2.298 | 4.220 | 2.401 | 3.469 | 2.472 | 5.781 | 1.944 |
|  | 0.50 | 4.619 | 1.991 | 4.363 | 2.094 | 3.994 | 2.190 | 3.133 | 2.206 | 5.614 | 1.696 |
|  | 0.75 | 3.364 | 1.235 | 3.116 | 1.329 | 2.725 | 1.389 | 1.986 | 1.259 | 4.447 | 0.954 |
|  | 1.00 | 2.174 | 0.784 | 1.914 | 0.827 | 1.622 | 0.785 | 1.245 | 0.550 | 3.279 | 0.574 |
|  | 1.50 | 1.105 | 0.307 | 1.043 | 0.204 | 1.013 | 0.114 | 1.001 | 0.038 | 2.078 | 0.268 |
|  | 2.00 | 1.000 | 0.019 | 1.000 | 0.005 | 1.000 | 0.000 | 1.000 | 0.000 | 1.910 | 0.286 |
| 0.75 | 0.00 | 26.146 | 20.651 | 24.449 | 18.947 | 22.784 | 17.554 | 20.278 | 16.644 | 29.282 | 22.840 |
|  | 0.10 | 26.071 | 20.457 | 24.283 | 18.693 | 22.679 | 17.684 | 20.071 | 16.595 | 29.230 | 22.876 |
|  | 0.25 | 21.821 | 16.239 | 20.087 | 14.598 | 18.858 | 13.865 | 16.295 | 13.414 | 24.383 | 17.620 |
|  | 0.50 | 8.163 | 4.458 | 7.764 | 4.489 | 7.190 | 4.521 | 5.987 | 4.755 | 9.326 | 4.354 |
|  | 0.75 | 3.827 | 1.859 | 3.529 | 1.903 | 3.179 | 1.959 | 2.512 | 1.831 | 4.924 | 1.583 |
|  | 1.00 | 2.284 | 1.071 | 2.020 | 1.087 | 1.828 | 1.025 | 1.483 | 0.856 | 3.376 | 0.868 |
|  | 1.50 | 1.217 | 0.438 | 1.133 | 0.359 | 1.077 | 0.283 | 1.025 | 0.165 | 2.170 | 0.403 |
|  | 2.00 | 1.010 | 0.101 | 1.004 | 0.073 | 1.001 | 0.039 | 1.000 | 0.012 | 1.816 | 0.390 |
| 0.90 | 0.00 | 198.424 | 194.081 | 188.241 | 186.146 | 173.917 | 173.672 | 154.140 | 167.376 | 214.507 | 206.942 |
|  | 0.10 | 147.386 | 143.397 | 135.694 | 132.815 | 126.643 | 127.677 | 111.522 | 120.248 | 159.722 | 153.218 |
|  | 0.25 | 38.146 | 32.776 | 35.117 | 30.579 | 32.039 | 28.357 | 27.554 | 26.687 | 42.633 | 35.954 |
|  | 0.50 | 8.270 | 5.161 | 7.819 | 5.172 | 7.244 | 5.181 | 5.979 | 5.189 | 9.583 | 5.090 |
|  | 0.75 | 3.830 | 2.136 | 3.556 | 2.158 | 3.203 | 2.157 | 2.596 | 2.018 | 4.964 | 1.879 |
|  | 1.00 | 2.312 | 1.194 | 2.116 | 1.192 | 1.902 | 1.150 | 1.586 | 0.998 | 3.401 | 1.018 |
|  | 1.50 | 1.277 | 0.502 | 1.195 | 0.446 | 1.124 | 0.366 | 1.058 | 0.260 | 2.206 | 0.479 |
|  | 2.00 | 1.028 | 0.166 | 1.013 | 0.118 | 1.006 | 0.083 | 1.001 | 0.043 | 1.780 | 0.429 |
| 1.00 | 0.00 | 369.800 | 374.773 | 371.766 | 385.269 | 370.499 | 394.751 | 370.973 | 440.843 | 369.211 | 365.107 |
|  | 0.10 | 169.640 | 169.406 | 162.023 | 164.178 | 153.926 | 160.530 | 137.670 | 161.214 | 180.288 | 174.944 |
|  | 0.25 | 33.342 | 29.477 | 31.289 | 27.931 | 28.826 | 26.728 | 24.347 | 25.339 | 37.803 | 32.299 |
|  | 0.50 | 7.943 | 5.376 | 7.483 | 5.302 | 6.902 | 5.322 | 5.678 | 5.248 | 9.369 | 5.271 |
|  | 0.75 | 3.788 | 2.262 | 3.526 | 2.294 | 3.174 | 2.264 | 2.586 | 2.092 | 4.968 | 2.008 |
|  | 1.00 | 2.333 | 1.277 | 2.136 | 1.264 | 1.936 | 1.228 | 1.626 | 1.055 | 3.421 | 1.121 |
|  | 1.50 | 1.305 | 0.543 | 1.229 | 0.489 | 1.160 | 0.422 | 1.081 | 0.313 | 2.220 | 0.528 |
|  | 2.00 | 1.043 | 0.206 | 1.023 | 0.153 | 1.014 | 0.121 | 1.004 | 0.071 | 1.759 | 0.453 |


| Shifts |  | $\begin{aligned} & \hline \psi_{2}=0.03 \\ & \mathrm{~L}=2.630 \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=0.05 \\ & \mathrm{~L}=2.167 \end{aligned}$ |  | $\begin{aligned} & \hline \psi_{2}=0.07 \\ & \mathbf{L}=1.688 \end{aligned}$ |  | $\begin{gathered} \psi_{2}=0.1 \\ \mathrm{~L}=0.977 \end{gathered}$ |  | $\begin{gathered} \lambda=0.2 \\ \mathbf{L}=3.250 \end{gathered}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $b$ | $a$ | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL |
| 1.10 | 0.00 | 87.720 | 88.458 | 84.122 | 86.471 | 77.400 | 83.589 | 67.287 | 82.881 | 95.971 | 90.800 |
|  | 0.10 | 65.056 | 63.328 | 60.437 | 61.438 | 55.847 | 59.500 | 47.252 | 56.974 | 71.193 | 65.244 |
|  | 0.25 | 24.378 | 21.856 | 22.405 | 20.413 | 20.722 | 20.044 | 17.025 | 18.988 | 27.866 | 22.882 |
|  | 0.50 | 7.422 | 5.362 | 6.951 | 5.296 | 6.263 | 5.166 | 5.151 | 5.004 | 9.026 | 5.277 |
|  | 0.75 | 3.702 | 2.366 | 3.426 | 2.388 | 3.094 | 2.319 | 2.494 | 2.075 | 4.971 | 2.164 |
|  | 1.00 | 2.331 | 1.351 | 2.149 | 1.335 | 1.944 | 1.259 | 1.652 | 1.117 | 3.457 | 1.216 |
|  | 1.50 | 1.337 | 0.585 | 1.257 | 0.530 | 1.185 | 0.469 | 1.103 | 0.358 | 2.233 | 0.585 |
|  | 2.00 | 1.059 | 0.241 | 1.037 | 0.193 | 1.021 | 0.149 | 1.010 | 0.105 | 1.746 | 0.478 |
| 1.25 | 0.00 | 17.420 | 15.809 | 16.125 | 15.219 | 14.566 | 14.635 | 11.379 | 13.762 | 20.488 | 16.080 |
|  | 0.10 | 16.290 | 14.576 | 15.004 | 14.235 | 13.468 | 13.639 | 10.564 | 12.631 | 19.423 | 15.129 |
|  | 0.25 | 11.879 | 10.145 | 11.039 | 9.876 | 9.841 | 9.608 | 7.664 | 8.810 | 14.358 | 10.235 |
|  | 0.50 | 5.998 | 4.562 | 5.542 | 4.503 | 4.932 | 4.349 | 3.877 | 3.999 | 7.778 | 4.431 |
|  | 0.75 | 3.472 | 2.376 | 3.140 | 2.291 | 2.815 | 2.217 | 2.296 | 1.939 | 4.807 | 2.199 |
|  | 1.00 | 2.296 | 1.409 | 2.113 | 1.379 | 1.918 | 1.306 | 1.620 | 1.111 | 3.438 | 1.317 |
|  | 1.50 | 1.369 | 0.637 | 1.289 | 0.589 | 1.219 | 0.528 | 1.128 | 0.417 | 2.260 | 0.663 |
|  | 2.00 | 1.084 | 0.287 | 1.056 | 0.239 | 1.036 | 0.197 | 1.017 | 0.136 | 1.742 | 0.514 |
| 1.50 | 0.00 | 5.190 | 4.259 | 4.677 | 4.098 | 4.120 | 3.909 | 3.147 | 3.352 | 7.006 | 4.097 |
|  | 0.10 | 5.062 | 4.092 | 4.593 | 3.975 | 4.028 | 3.806 | 3.104 | 3.344 | 6.953 | 4.064 |
|  | 0.25 | 4.655 | 3.785 | 4.229 | 3.600 | 3.714 | 3.440 | 2.856 | 2.940 | 6.455 | 3.626 |
|  | 0.50 | 3.628 | 2.781 | 3.290 | 2.692 | 2.905 | 2.523 | 2.291 | 2.151 | 5.266 | 2.700 |
|  | 0.75 | 2.712 | 1.928 | 2.472 | 1.852 | 2.189 | 1.713 | 1.812 | 1.432 | 4.162 | 1.889 |
|  | 1.00 | 2.071 | 1.331 | 1.899 | 1.270 | 1.725 | 1.173 | 1.483 | 0.960 | 3.252 | 1.336 |
|  | 1.50 | 1.392 | 0.687 | 1.306 | 0.630 | 1.238 | 0.565 | 1.145 | 0.452 | 2.258 | 0.767 |
|  | 2.00 | 1.119 | 0.350 | 1.084 | 0.300 | 1.059 | 0.257 | 1.033 | 0.198 | 1.731 | 0.572 |
| 2.00 | 0.00 | 1.963 | 1.325 | 1.788 | 1.216 | 1.637 | 1.122 | 1.405 | 0.858 | 3.143 | 1.425 |
|  | 0.10 | 1.962 | 1.319 | 1.792 | 1.225 | 1.627 | 1.098 | 1.405 | 0.851 | 3.132 | 1.435 |
|  | 0.25 | 1.918 | 1.280 | 1.759 | 1.185 | 1.606 | 1.062 | 1.393 | 0.845 | 3.091 | 1.388 |
|  | 0.50 | 1.821 | 1.185 | 1.666 | 1.078 | 1.533 | 0.973 | 1.350 | 0.776 | 2.944 | 1.305 |
|  | 0.75 | 1.665 | 1.014 | 1.558 | 0.959 | 1.434 | 0.929 | 1.281 | 0.666 | 2.742 | 1.162 |
|  | 1.00 | 1.533 | 0.880 | 1.435 | 0.803 | 1.347 | 0.723 | 1.222 | 0.573 | 2.518 | 1.025 |
|  | 1.50 | 1.279 | 0.576 | 1.125 | 0.554 | 1.281 | 6.769 | 1.211 | 8.990 | 2.044 | 0.785 |
|  | 2.00 | 1.118 | 0.361 | 1.094 | 0.322 | 1.258 | 9.559 | 1.040 | 0.218 | 1.684 | 0.633 |
| 2.50 | 0.00 | 1.358 | 0.693 | 1.288 | 0.620 | 1.226 | 0.554 | 1.144 | 0.427 | 2.157 | 0.924 |
|  | 0.10 | 1.356 | 0.686 | 1.291 | 0.625 | 1.223 | 0.546 | 1.149 | 0.438 | 2.154 | 0.913 |
|  | 0.25 | 1.356 | 0.696 | 1.287 | 0.629 | 1.226 | 0.549 | 1.143 | 0.436 | 2.131 | 0.914 |
|  | 0.50 | 1.325 | 0.650 | 1.267 | 0.595 | 1.206 | 0.521 | 1.132 | 0.407 | 2.103 | 0.891 |
|  | 0.75 | 1.293 | 0.611 | 1.240 | 0.588 | 1.178 | 0.476 | 1.119 | 0.389 | 2.029 | 0.846 |
|  | 1.00 | 1.253 | 0.561 | 1.202 | 0.504 | 1.153 | 0.438 | 1.099 | 0.346 | 1.951 | 0.809 |
|  | 1.50 | 1.173 | 0.450 | 1.137 | 0.412 | 1.101 | 0.348 | 1.070 | 0.445 | 1.753 | 0.709 |
|  | 2.00 | 1.110 | 1.108 | 1.092 | 1.211 | 1.112 | 4.028 | 1.065 | 1.867 | 1.549 | 0.611 |
| 3.00 | 0.00 | 1.168 | 0.444 | 1.131 | 0.388 | 1.100 | 0.340 | 1.064 | 0.267 | 1.696 | 0.710 |
|  | 0.10 | 1.163 | 0.434 | 1.129 | 0.386 | 1.098 | 0.336 | 1.064 | 0.264 | 1.695 | 0.712 |
|  | 0.25 | 1.162 | 0.437 | 1.130 | 0.386 | 1.099 | 0.341 | 1.061 | 0.262 | 1.690 | 0.712 |
|  | 0.50 | 1.154 | 0.421 | 1.119 | 0.366 | 1.093 | 0.323 | 1.058 | 0.252 | 1.670 | 0.699 |
|  | 0.75 | 1.145 | 0.406 | 1.112 | 0.363 | 1.086 | 0.312 | 1.056 | 0.246 | 1.646 | 0.690 |
|  | 1.00 | 1.129 | 0.384 | 1.104 | 0.345 | 1.080 | 0.303 | 1.050 | 0.235 | 1.604 | 0.667 |
|  | 1.50 | 1.098 | 0.334 | 1.078 | 0.297 | 1.056 | 0.251 | 1.036 | 0.254 | 1.502 | 0.614 |
|  | 2.00 | 1.070 | 0.447 | 1.051 | 0.236 | 1.039 | 0.278 | 1.024 | 0.171 | 1.397 | 0.552 |

Table 3
ARLs and SDRLs of Max-EEWMA Chart and Max-EWMA Chart for $\boldsymbol{\psi}_{1}=\lambda=0.3$

| Shifts |  | $\begin{aligned} & \psi_{2}=0.03 \\ & \mathrm{~L}=3.002 \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=0.05 \\ & \mathrm{~L}=2.737 \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=0.07 \\ & \mathrm{~L}=2.459 \end{aligned}$ |  | $\begin{gathered} \psi_{2}=0.1 \\ \mathrm{~L}=2.019 \end{gathered}$ |  | $\begin{gathered} \lambda=0.3 \\ \mathrm{~L}=3.344 \end{gathered}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $b$ | $a$ | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL |
| 0.25 | 0.00 | 1.927 | 0.635 | 1.819 | 0.653 | 1.693 | 0.661 | 1.486 | 0.629 | 2.535 | 0.549 |
|  | 0.10 | 1.932 | 0.639 | 1.818 | 0.658 | 1.688 | 0.658 | 1.491 | 0.623 | 2.541 | 0.550 |
|  | 0.25 | 1.931 | 0.627 | 1.817 | 0.654 | 1.689 | 0.662 | 1.492 | 0.626 | 2.537 | 0.549 |
|  | 0.50 | 1.934 | 0.634 | 1.822 | 0.663 | 1.703 | 0.675 | 1.498 | 0.633 | 2.534 | 0.547 |
|  | 0.75 | 1.928 | 0.638 | 1.830 | 0.667 | 1.707 | 0.679 | 1.503 | 0.644 | 2.537 | 0.547 |
|  | 1.00 | 1.856 | 0.547 | 1.748 | 0.577 | 1.626 | 0.589 | 1.381 | 0.540 | 2.501 | 0.506 |
|  | 1.50 | 1.043 | 0.202 | 1.010 | 0.103 | 1.002 | 0.045 | 1.000 | 0.011 | 1.999 | 0.036 |
|  | 2.00 | 1.000 | 0.000 | 1.000 | 0.000 | 1.000 | 0.000 | 1.000 | 0.000 | 1.397 | 0.489 |
| 0.50 | 0.00 | 5.629 | 2.809 | 5.517 | 2.806 | 5.435 | 2.845 | 5.126 | 2.893 | 6.161 | 2.767 |
|  | 0.10 | 5.667 | 2.894 | 5.536 | 2.818 | 5.399 | 2.833 | 5.104 | 2.876 | 6.176 | 2.758 |
|  | 0.25 | 5.634 | 2.800 | 5.579 | 2.845 | 5.421 | 2.818 | 5.155 | 2.907 | 6.174 | 2.763 |
|  | 0.50 | 5.421 | 2.534 | 5.352 | 2.563 | 5.210 | 2.584 | 4.957 | 2.681 | 5.948 | 2.467 |
|  | 0.75 | 3.877 | 1.413 | 3.798 | 1.450 | 3.677 | 1.511 | 3.449 | 1.642 | 4.382 | 1.225 |
|  | 1.00 | 2.459 | 0.827 | 2.370 | 0.879 | 2.246 | 0.929 | 2.008 | 0.980 | 3.041 | 0.661 |
|  | 1.50 | 1.206 | 0.406 | 1.134 | 0.343 | 1.087 | 0.285 | 1.035 | 0.188 | 1.999 | 0.189 |
|  | 2.00 | 1.001 | 0.036 | 1.000 | 0.021 | 1.000 | 0.016 | 1.000 | 0.008 | 1.449 | 0.497 |
| 0.75 | 0.00 | 43.155 | 39.134 | 40.819 | 36.343 | 38.848 | 34.644 | 35.907 | 31.594 | 47.359 | 42.514 |
|  | 0.10 | 42.507 | 38.004 | 40.708 | 36.365 | 38.741 | 34.266 | 35.370 | 30.735 | 47.197 | 42.589 |
|  | 0.25 | 36.014 | 31.491 | 34.247 | 29.639 | 32.208 | 27.661 | 29.949 | 25.623 | 39.550 | 34.971 |
|  | 0.50 | 10.695 | 6.970 | 10.281 | 6.612 | 9.985 | 6.423 | 9.451 | 6.218 | 11.665 | 7.309 |
|  | 0.75 | 4.379 | 2.179 | 4.265 | 2.171 | 4.146 | 2.229 | 3.848 | 2.281 | 4.959 | 2.029 |
|  | 1.00 | 2.558 | 1.144 | 2.463 | 1.179 | 2.354 | 1.212 | 2.141 | 1.227 | 3.157 | 0.980 |
|  | 1.50 | 1.313 | 0.504 | 1.253 | 0.477 | 1.198 | 0.437 | 1.128 | 0.368 | 2.001 | 0.408 |
|  | 2.00 | 1.020 | 0.143 | 1.013 | 0.116 | 1.008 | 0.089 | 1.003 | 0.062 | 1.462 | 0.499 |
| 0.90 | 0.00 | 287.249 | 286.347 | 276.117 | 275.772 | 269.983 | 272.165 | 254.857 | 257.569 | 299.460 | 293.569 |
|  | 0.10 | 217.433 | 215.160 | 210.320 | 208.816 | 203.714 | 202.804 | 191.203 | 191.939 | 230.117 | 224.655 |
|  | 0.25 | 61.090 | 58.194 | 57.704 | 53.868 | 54.440 | 51.245 | 51.413 | 48.718 | 66.002 | 61.581 |
|  | 0.50 | 10.289 | 7.245 | 9.958 | 7.070 | 9.652 | 6.814 | 9.040 | 6.594 | 11.269 | 7.645 |
|  | 0.75 | 4.325 | 2.409 | 4.210 | 2.441 | 4.079 | 2.462 | 3.778 | 2.488 | 4.946 | 2.283 |
|  | 1.00 | 2.558 | 1.293 | 2.475 | 1.315 | 2.389 | 1.345 | 2.200 | 1.342 | 3.190 | 1.135 |
|  | 1.50 | 1.367 | 0.563 | 1.311 | 0.542 | 1.261 | 0.520 | 1.188 | 0.467 | 2.002 | 0.508 |
|  | 2.00 | 1.046 | 0.212 | 1.031 | 0.176 | 1.023 | 0.151 | 1.013 | 0.116 | 1.471 | 0.503 |
| 1.00 | 0.00 | 371.865 | 376.106 | 369.095 | 373.644 | 370.813 | 375.749 | 371.947 | 386.804 | 373.733 | 369.780 |
|  | 0.10 | 209.774 | 208.190 | 205.970 | 206.217 | 200.174 | 200.798 | 192.295 | 197.184 | 218.830 | 215.287 |
|  | 0.25 | 47.401 | 44.696 | 45.349 | 42.734 | 43.728 | 41.413 | 40.396 | 38.588 | 50.703 | 46.826 |
|  | 0.50 | 9.609 | 7.161 | 9.240 | 6.842 | 8.968 | 6.691 | 8.399 | 6.554 | 10.520 | 7.262 |
|  | 0.75 | 4.231 | 2.534 | 4.147 | 2.550 | 3.998 | 2.556 | 3.723 | 2.581 | 4.909 | 2.416 |
|  | 1.00 | 2.574 | 1.377 | 2.488 | 1.395 | 2.378 | 1.417 | 2.210 | 1.427 | 3.206 | 1.235 |
|  | 1.50 | 1.400 | 0.604 | 1.346 | 0.586 | 1.289 | 0.560 | 1.223 | 0.516 | 2.002 | 0.564 |
|  | 2.00 | 1.063 | 0.248 | 1.050 | 0.221 | 1.037 | 0.193 | 1.023 | 0.155 | 1.480 | 0.509 |


| Shifts |  | $\begin{aligned} & \psi_{2}=0.03 \\ & \mathrm{~L}=3.002 \end{aligned}$ |  | $\begin{aligned} & \boldsymbol{\psi}_{2}=0.05 \\ & \mathrm{~L}=2.737 \end{aligned}$ |  | $\begin{aligned} & \psi_{2}=0.07 \\ & \mathrm{~L}=2.459 \end{aligned}$ |  | $\begin{gathered} \psi_{2}=0.1 \\ \mathrm{~L}=2.019 \end{gathered}$ |  | $\begin{gathered} \lambda=0.3 \\ L=3.344 \end{gathered}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $b$ | $a$ | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL | ARL | SDRL |
| 1.10 | 0.00 | 102.208 | 101.355 | 99.405 | 101.402 | 95.766 | 98.212 | 93.106 | 97.426 | 106.428 | 102.871 |
|  | 0.10 | 78.103 | 76.511 | 75.667 | 75.570 | 73.649 | 74.048 | 69.460 | 72.252 | 82.146 | 78.781 |
|  | 0.25 | 30.996 | 28.960 | 29.470 | 27.316 | 28.851 | 27.360 | 26.392 | 25.645 | 33.191 | 29.442 |
|  | 0.50 | 8.667 | 6.604 | 8.296 | 6.353 | 8.070 | 6.307 | 7.486 | 6.106 | 9.656 | 6.598 |
|  | 0.75 | 4.107 | 2.608 | 3.982 | 2.619 | 3.845 | 2.608 | 3.588 | 2.609 | 4.858 | 2.496 |
|  | 1.00 | 2.563 | 1.465 | 2.466 | 1.466 | 2.366 | 1.464 | 2.199 | 1.455 | 3.221 | 1.336 |
|  | 1.50 | 1.427 | 0.642 | 1.374 | 0.633 | 1.327 | 0.611 | 1.260 | 0.572 | 2.006 | 0.617 |
|  | 2.00 | 1.086 | 0.290 | 1.068 | 0.260 | 1.052 | 0.231 | 1.035 | 0.197 | 1.487 | 0.517 |
| 1.25 | 0.00 | 20.616 | 19.125 | 19.830 | 18.906 | 18.847 | 17.922 | 17.533 | 17.529 | 22.791 | 19.560 |
|  | 0.10 | 19.220 | 17.657 | 18.221 | 16.982 | 17.634 | 16.606 | 16.189 | 16.136 | 21.296 | 18.406 |
|  | 0.25 | 13.885 | 12.097 | 13.274 | 11.780 | 12.687 | 11.541 | 11.735 | 11.188 | 15.390 | 12.346 |
|  | 0.50 | 6.765 | 5.189 | 6.567 | 5.204 | 6.304 | 5.137 | 5.751 | 4.962 | 7.896 | 5.247 |
|  | 0.75 | 3.804 | 2.542 | 3.650 | 2.546 | 3.539 | 2.543 | 3.243 | 2.488 | 4.613 | 2.460 |
|  | 1.00 | 2.519 | 1.516 | 2.409 | 1.509 | 2.309 | 1.511 | 2.180 | 1.519 | 3.199 | 1.414 |
|  | 1.50 | 1.460 | 0.694 | 1.421 | 0.695 | 1.367 | 0.671 | 1.287 | 0.617 | 2.024 | 0.697 |
|  | 2.00 | 1.112 | 0.333 | 1.094 | 0.310 | 1.078 | 0.289 | 1.053 | 0.242 | 1.495 | 0.532 |
| 1.50 | 0.00 | 5.691 | 4.628 | 5.442 | 4.535 | 5.131 | 4.353 | 4.659 | 4.253 | 6.849 | 4.556 |
|  | 0.10 | 5.568 | 4.472 | 5.346 | 4.407 | 5.118 | 4.354 | 4.588 | 4.158 | 6.715 | 4.471 |
|  | 0.25 | 5.149 | 4.052 | 4.908 | 4.006 | 4.696 | 3.943 | 4.199 | 3.768 | 6.293 | 4.050 |
|  | 0.50 | 4.019 | 2.969 | 3.793 | 2.893 | 3.653 | 2.901 | 3.305 | 2.779 | 4.970 | 2.913 |
|  | 0.75 | 2.979 | 2.065 | 2.848 | 2.031 | 2.706 | 1.993 | 2.483 | 1.922 | 3.816 | 1.998 |
|  | 1.00 | 2.234 | 1.408 | 2.170 | 1.415 | 2.080 | 1.408 | 1.908 | 1.334 | 2.964 | 1.388 |
|  | 1.50 | 1.474 | 0.748 | 1.428 | 0.732 | 1.378 | 0.708 | 1.305 | 0.660 | 2.005 | 0.793 |
|  | 2.00 | 1.152 | 0.393 | 1.126 | 0.363 | 1.110 | 0.351 | 1.079 | 0.299 | 1.516 | 0.569 |
| 2.00 | 0.00 | 2.109 | 1.414 | 2.008 | 1.367 | 1.925 | 1.322 | 1.756 | 1.203 | 2.827 | 1.437 |
|  | 0.10 | 2.095 | 1.410 | 2.008 | 1.362 | 1.899 | 1.302 | 1.756 | 1.196 | 2.830 | 1.460 |
|  | 0.25 | 2.055 | 1.342 | 1.969 | 1.311 | 1.874 | 1.270 | 1.744 | 1.198 | 2.786 | 1.415 |
|  | 0.50 | 1.937 | 1.236 | 1.858 | 1.215 | 1.779 | 1.161 | 1.669 | 1.099 | 2.649 | 1.309 |
|  | 0.75 | 1.791 | 1.105 | 1.715 | 1.060 | 1.645 | 1.023 | 1.539 | 0.936 | 2.436 | 1.166 |
|  | 1.00 | 1.626 | 0.945 | 1.571 | 0.908 | 1.505 | 0.866 | 1.426 | 0.802 | 2.229 | 1.028 |
|  | 1.50 | 1.354 | 1.042 | 1.274 | 0.587 | 1.272 | 0.592 | 1.246 | 0.553 | 1.805 | 0.773 |
|  | 2.00 | 1.156 | 0.397 | 1.114 | 0.394 | 1.094 | 0.311 | 1.096 | 0.353 | 1.480 | 0.597 |
| 2.50 | 0.00 | 1.425 | 0.743 | 1.390 | 0.723 | 1.337 | 0.678 | 1.280 | 0.611 | 1.896 | 0.889 |
|  | 0.10 | 1.428 | 0.750 | 1.385 | 0.712 | 1.341 | 0.669 | 1.274 | 0.615 | 1.891 | 0.897 |
|  | 0.25 | 1.412 | 0.729 | 1.375 | 0.706 | 1.321 | 0.647 | 1.271 | 0.597 | 1.892 | 0.878 |
|  | 0.50 | 1.393 | 0.716 | 1.353 | 0.677 | 1.310 | 0.638 | 1.256 | 0.583 | 1.848 | 0.853 |
|  | 0.75 | 1.350 | 0.661 | 1.310 | 0.629 | 1.285 | 0.612 | 1.231 | 0.546 | 1.787 | 0.820 |
|  | 1.00 | 1.303 | 0.611 | 1.272 | 0.580 | 1.246 | 0.556 | 1.196 | 0.495 | 1.715 | 0.768 |
|  | 1.50 | 1.207 | 0.813 | 1.191 | 0.899 | 1.164 | 0.448 | 1.162 | 2.482 | 1.541 | 0.666 |
|  | 2.00 | 1.128 | 0.822 | 1.138 | 2.023 | 1.177 | 4.254 | 1.158 | 4.093 | 1.369 | 0.550 |
| 3.00 | 0.00 | 1.204 | 0.482 | 1.177 | 0.450 | 1.150 | 0.420 | 1.127 | 0.384 | 1.503 | 0.665 |
|  | 0.10 | 1.201 | 0.483 | 1.173 | 0.445 | 1.155 | 0.423 | 1.122 | 0.378 | 1.501 | 0.662 |
|  | 0.25 | 1.196 | 0.470 | 1.174 | 0.448 | 1.156 | 0.430 | 1.122 | 0.375 | 1.504 | 0.663 |
|  | 0.50 | 1.190 | 0.466 | 1.171 | 0.445 | 1.145 | 0.406 | 1.119 | 0.372 | 1.484 | 0.653 |
|  | 0.75 | 1.180 | 0.453 | 1.157 | 0.427 | 1.136 | 0.395 | 1.110 | 0.356 | 1.461 | 0.631 |
|  | 1.00 | 1.159 | 0.423 | 1.136 | 0.394 | 1.122 | 0.376 | 1.100 | 0.337 | 1.424 | 0.609 |
|  | 1.50 | 1.115 | 0.354 | 1.105 | 0.341 | 1.094 | 0.329 | 1.072 | 0.362 | 1.344 | 0.548 |
|  | 2.00 | 1.082 | 0.307 | 1.075 | 0.381 | 1.066 | 0.453 | 1.051 | 0.376 | 1.261 | 0.480 |

## 5. ILLUSTRATION EXAMPLE

We used data set given by (Costa \& Castagliola, 2011) and (Hu et al., 2015), to evaluate the implementation of developed chart. The data consists of 200 values during the procedure of yogurt packing in a cup with the quality characteristic " $Y$ " set at 125 grams. The in-control parameters $\mu_{o}=124.9$ and $\sigma_{o}=0.76$ mean and standard deviation, respectively, have been calculated after the long-term phase-I study. To retain the quality of the cup filling, after every hour the quality control specialists pick a sample and record its weight twice. In the above-mentioned papers, 20 samples of size 5 have been formed, and we utilize the same data set in this paper, but we consider the first 100 data values as in-control and the rest of the 100 values as shifted.

Table 4
Max-EEWMA Statistics and Max-EWMA Statistics for Yogurt Filling Data Set

| Sample | MAX-EEWMA | $\boldsymbol{U C L}$ | MAX-EWMA | $\boldsymbol{U C L}_{\boldsymbol{1}}$ |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 0.2718588 | 0.9001873 | 0.2718588 | 1.064736 |
| 2 | 0.1502446 | 0.9001873 | 0.1931716 | 1.064736 |
| 3 | 0.1888789 | 0.9001873 | 0.2618548 | 1.064736 |
| 4 | 0.3364976 | 0.9001873 | 0.3248089 | 1.064736 |
| 5 | 0.3199126 | 0.9001873 | 0.4363788 | 1.064736 |
| 6 | 0.2831080 | 0.9001873 | 0.3959245 | 1.064736 |
| 7 | 0.3084560 | 0.9001873 | 0.4240572 | 1.064736 |
| 8 | 0.4238823 | 0.9001873 | 0.4607316 | 1.064736 |
| 9 | 0.3518010 | 0.9001873 | 0.4645682 | 1.064736 |
| 10 | 0.8265119 | 0.9001873 | 0.9259101 | 1.064736 |
| 11 | 0.3869105 | 0.9001873 | 0.4904952 | 1.064736 |
| 12 | 0.5703074 | 0.9001873 | 0.5805294 | 1.064736 |
| 13 | 0.8086730 | 0.9001873 | 1.1434820 | 1.064736 |
| 14 | 0.8602045 | 0.9001873 | 1.3867137 | 1.064736 |
| 15 | 1.5515119 | 0.9001873 | 2.1226628 | 1.064736 |
| 16 | 1.6040796 | 0.9001873 | 2.4124951 | 1.064736 |
| 17 | 1.8161535 | 0.9001873 | 2.6596604 | 1.064736 |
| 18 | 1.9464108 | 0.9001873 | 2.8044331 | 1.064736 |
| 19 | 2.1572042 | 0.9001873 | 2.9873333 | 1.064736 |
| 20 | 2.1780362 | 0.9001873 | 2.9983125 | 1.064736 |

We attain $\mathrm{ARL}_{0}=370$ by using $L=3.427, A=0, B=1$, and $\lambda=0.2$ by using the first 100 values of the data set. After that, we select 20 samples of each size 5 of the yogurt cup in such a way that the first 10 samples are selected from in-control values and the rest of the 10 values are selected from the last 100 shifted values. Afterward, we calculated the proposed statistic Max-EEWMA as well as $U C L$ from all 20 values. Values of statistics and $U C L s$ are given in Table 4.


Figure 1: Max-EEWMA Control Chart


Figure 2: Max-EWMA Control Chart

Figure 1 shows a clear picture of Table 4 data, which shows the proposed Max-EEWMA control chart. In this chart, $U C L$ for proposed chart and in Figure $2 U C L_{1}$ for the existing chart is represented as a horizontal line. It can easily be observed that proposed chart indicates the out-of-control signal at $10^{\text {th }}$ value while the existing chart indicates it at $13^{\text {th }}$ sample. Therefore, it is clear from Figures 1-2 that proposed chart performed better than existing chart.

## 6. MAIN FINDINGS

Results regarding Max-EEWMA control chart are presented in Tables 1-3, Table 1 shows the $A R L s$ and $S D R L s$ for $\psi_{1}=0.15$, Table 2 for $\psi_{1}=0.2$ and Table 3 for $\psi_{1}=0.3$. The results of Max-EEWMA statistics are presented in Table 4 with Max-EWMA statistics. According to this study, the major findings of the Max-EEWMA chart are mentioned below.

1. When $a=0$ and $b=1$, then the process is without shift, and it indicates that process is in control with $A R L_{0}$. In Table 1, for $\psi_{2}=0.05$ the $A R L$ is 370.10. In Table 2, for $\psi_{2}=0.07$ the $A R L$ is 370.49 . In Table 3, for $\psi_{2}=0.1$ the $A R L$ is 371.94.
2. All table values reveal that when mean shifts " $a$ " increases from 0.00 to $0.10,0.25$, $0.50,0.75,1.00,1.50$, and 2.00 , values of respective $A R L s$ and $S D R L s$ minimize, for all various values in variance " $b$ ". It reveals that suggested chart is more efficient in identifying mean shifts early.
3. Same pattern is observed for " $b$ ", the variance shift. As the variance shift decreases from 1 to $0.25,0.50,0.75,0.90$, and increases to $1.10,1.25,1.50,2.00,2.50$, and 3.00, then both values of $A R L s \& S D R L s$ are decreased respectively with variation in mean shift " $a$ ". It can also be observed that variance shift also detected early, which also indicates the efficiency of the developed chart.
4. In all Tables 1-3, the last column shows the comparison with existing Max-EWMA control chart in terms of ARLs and reveals efficiency of our proposed MaxEEWMA control chart for combined detection of mean and variance shifts.
5. As values of $\psi_{2}$ increase from 0.03 to $0.05,0.07$, and 0.1 for different values of $\psi_{1}=0.15,0.2$, and 0.3 , the ARLs and SDRLs decrease. In Table 2, when $\psi_{1}=0.2$ and $\psi_{2}=0.05$, the value of $A R L$ is 24.283 for $b=0.75$ and $a=0.1$, for $\psi_{2}=0.07$ ARL is 22.679 .
6. Real-Life application detects out of control earlier than existing one which also support the simulations result which as well can be observe from Figure 1 and Figure 2 that proposed chart detect out of control at $10^{\text {th }}$ value and existing chart at $13^{\text {th }}$ value.

From the above-mentioned results and facts from calculations in ARL values tables, we can conclude that our developed Max-EEWMA control chart outperforms existing control charts. The proposed chart efficiently detects even smaller mean and variance shifts combinedly. The suggested control chart can examine both mean and variance process shifts concurrently with single statistics rather than two separate statistics for mean and variance.

## 7. CONCLUSION

In quality control field different types of control chart have been developed by different researchers but many researchers ignored the joint examining of mean and variance simultaneously. In this article, we addressed the issue of joint monitoring and developed a new control chart and named it Max-EEWMA control chart. The values of ARLs and SDRLs have been estimated and tables were created for numerous smoothing constant values with different mean and variance shifts. The comparisons to the existing MaxEWMA control chart were made in terms of ARLs and SDRLs, which reveal that the proposed chart identifies both mean and variance shifts quicker than the Max-EWMA chart. The real-life application of the Max-EEWMA control chart was also illustrated, and it also shows the efficiency of the developed chart. The proposed chart can be used in the industry for joint monitoring of the mean and variance shifts in the production procedure.

## DATA AVAILABILITY

The datasets used and/or analysed during the current study available from the corresponding author on reasonable request. Further, no experiments on humans and/or the use of human tissue samples were involved in this study.

## REFERENCES

1. Chatterjee, K., Koukouvinos, C. and Lappa, A. (2022). A joint monitoring of the process mean and variance with a TEWMA-Max control chart. Communications in Statistics-Theory and Methods, 52(22), 8069-8095.
2. Chen, G., Cheng, S.W. and Xie, H. (2001). Monitoring process mean and variability with one EWMA chart. Journal of Quality Technology, 33(2), 223-233.
3. Costa, A.F. and Castagliola, P. (2011). Effect of measurement error and autocorrelation on the X chart. Journal of Applied Statistics, 38(4), 661-673.
4. Engmann, G.M. and Han, D. (2022). The optimized CUSUM and EWMA multi-charts for jointly detecting a range of mean and variance change. Journal of Applied Statistics, 49(6), 1540-1558.
5. Haq, A. and Woodall, W.H. (2023). A critique of the use of modified and moving average-based EWMA control charts. Quality and Reliability Engineering International, 39(4), 1269-1276.
6. Hu, X., Castagliola, P., Sun, J. and Khoo, M.B. (2015). The effect of measurement errors on the synthetic chart. Quality and Reliability Engineering International, 31(8), 1769-1778.
7. Javaid, A., Noor-ul-Amin, M. and Hanif, M. (2020). Performance of Max-EWMA control chart for joint monitoring of mean and variance with measurement error. Communications in Statistics-Simulation and Computation, 52(1), 1-26.
8. Karoon, K., Areepong, Y. and Sukparungsee, S. (2022). Exact Solution of Average Run Length on Extended EWMA Control Chart for the First-Order Autoregressive Process. Thailand Statistician, 20(2), 395-411.
9. Khan, N., Aslam, M. and Albassam, M. (2023). Efficiency enhancement of the modified EWMA control method with conditional expected delay for change detection in processes. Front. Appl. Math. Stat. 9:1268340. doi: 10.3389/fams.2023.1268340
10. Khoo, M.B., Teh, S. and Wu, Z. (2010). Monitoring process mean and variability with one double EWMA chart. Communications in Statistics-Theory and Methods, 39(20), 3678-3694.
11. Naveed, M., Azam, M., Khan, N. and Aslam, M. (2018). Design of a control chart using extended EWMA statistic. Technologies, 6(4), 108.
12. Noor-ul-Amin, M., Arif, F. and Hanif, M. (2019). Joint monitoring of mean and variance using likelihood ratio test statistic under pair ranked set sampling scheme. Iranian Journal of Science and Technology, Transactions A: Science, 43(5), 24492460.
13. Ostadsharif Memar, A. and Niaki, S.T.A. (2011). The Max EWMAMS control chart for joint monitoring of process mean and variance with individual observations. Quality and Reliability Engineering International, 27(4), 499-514.
14. Page, E.S. (1954). Continuous inspection schemes. Biometrika, 41(1/2), 100-115.
15. Riaz, A., Noor-ul-Amin, M. and Dogu, E. (2022). Effect of measurement error on joint monitoring of process mean and coefficient of variation. Communications in StatisticsTheory and Methods, 51(19), 6863-6882.
16. Roberts, S. (1959). Control Chart Tests Based on Geometric Moving Averages. Technometrics, 239-250.
17. Xie, H. (1999). Contributions to qualimetry [PhD thesis]. Winnipeg, Canada: University of Manitoba.
