

**A CONFLUENT HYPERGEOMETRIC GENERALIZED  
INVERSE GAUSSIAN DISTRIBUTION**

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**ABSTRACT**

A new generalized extended inverse Gaussian density function involving a confluent hypergeometric function is defined. Closed form representations of a generalized extended inverse Gaussian density function and the corresponding moment generating function are provided in terms of Meijer's G-function. Some other statistical functions which are associated with the proposed distribution are also derived. Many distributions can be obtained as limiting cases of the proposed density function. This density is utilized to model an actual data set. The new distribution provides a better fit than related distributions as measured by the Anderson-Darling and Cramér-von Mises statistics. The proposed distribution could, for instance, find applications in the physical and biological sciences and in particular be helpful to researchers working in special functions as well as reliability analysis, survival models and diffraction theory.

**KEYWORDS**

Confluent hypergeometric function; Meijer's G-function; Generalized inverse Gaussian distribution; Lifetime data; Goodness-of-fit statistics.

**1. INTRODUCTION**

Some exponential distributions such as the gamma, Weibull and inverse Gaussian distributions have a wide range of applications in research areas such as reliability, survival analysis, queuing theory, the physical and biological sciences, hydrology, medicine, meteorology and engineering. In fact, the power function along with the exponential part which are both present in the gamma, Weibull and inverse Gaussian densities enable one to model a wide variety of data sets. To extend the scope of these distributions, many generalizations involving additional parameters have been considered, see for instance, Good (1953), Pham and Almhana (1995), Agarwal and Kalla (1996), Lee and Wang (2003), Chou and Huang (2004), Silva *et al.* (2006), Nadarajah and Kotz (2006), Nadarajah (2008), Provost *et al.* (2011), Provost and Mabrouk (2011), Lemonte and Cordeiro (2011), Kumar and Vellaisamy (2012), Saboor and Ahmad (2012), Saboor *et al.* (2012), Badmus *et al.* (2013), Cordeiro *et al.* (2013b), Cordeiro *et al.* (2013a), Cordeiro *et al.* (2013c), Cordeiro *et al.* (2013d), Cordeiro and Lemonte (2013), Cordeiro *et al.* (2014a), Gómez-

Déniz *et al.* (2013), Favaro and Lijoi (2013), Nagatsukaa and Balakrishnan (2013), Saboor and Ahmad (2013), Cordeiro *et al.* (2014b), Peng and Yan (2014), Saboor *et al.* (2014a), Saboor *et al.* (2014b), Saboor and Pogány (2014) and Tojeiro *et al.* (2014).

A generalized extended inverse Gaussian density function involving a confluent hypergeometric function is defined in Section 2. Graphical representations of the effects of the parameters are also included in Section 2. Explicit representations of certain statistical functions are provided in the Section 3. The parameter estimation technique described in Section 3.1 is utilized in connection with the modeling of a data set. Section 4 includes some concluding remarks.

## 2. A CONFLUENT HYPERGEOMETRIC GENERALIZED INVERSE GAUSSIAN DISTRIBUTION

This paper proposes a confluent hypergeometric generalized inverse Gaussian distribution (CHGIG) whose associated density function is defined as follows:

$$f(x) = C x^{m-1} \exp(-p_1 x - p_2 x^{-1}) {}_1F_1(\lambda; b; -\alpha x), \quad x > 0, \quad (1)$$

where  $f(x) > 0$  whenever  $m > 0, p_1 > 0, p_2 > 0, \alpha \geq 0, \lambda, b \neq 0, -1, -2, \dots$  and  $f(x) = 0$  elsewhere,  ${}_1F_1(\lambda; b; z) = \sum_{k=0}^{\infty} \frac{(\lambda)_k z^k}{(b)_k k!}, (\theta)_k = \Gamma(\theta + k) / \Gamma(\theta)$  denoting the Pochhammer function and  $\Re(b_1) > 0, \Re(b_2) > 0, \Re(b) > \Re(\lambda), \Re(b) \neq 0, -1, -2, \dots$ , see (Rainville, 1960) and

$$\begin{aligned} C^{-1} &= \Gamma^{(\Theta)}(m) = \int_0^{\infty} t^{m-1} \exp(-p_1 t - p_2 t^{-1}) {}_1F_1(\lambda; b; -\alpha t) dt, \\ &= \frac{\Gamma(b)}{\Gamma(\lambda)} \sum_{n=0}^{\infty} \frac{(p_1 p_2)^n}{n!} \left( p_1^{-m} G_{3,3}^{2,2} \left( \alpha/p_1 \left| \begin{matrix} 1-m, 1-\lambda, -m+n+1 \\ 0, 1-m, 1-b \end{matrix} \right. \right) \right. \\ &\quad \left. - p_2^m G_{2,4}^{2,2} \left( p_2 \alpha \left| \begin{matrix} 1-m, 1-\lambda \\ 0, 1-m, 1-b, -m-n \end{matrix} \right. \right) \right), \end{aligned} \quad (2)$$

where  $\Theta = \{\lambda, b, p_1, p_2, \alpha\}, \Re(b_1) > 0, \Re(b_2) > 0, -\infty < \Re(\alpha) < \infty, \Gamma^{(\Theta)}(m)$  is a generalized extended gamma function (Saboor *et al.*, 2013),  $\Re(b), \Re(\lambda), \Re(m) \neq 0, -1, -2, \dots$ , and the symbol  $G_{p,q}^{m,n}(\cdot)$  denotes Meijer's G-function (Meijer, 1946) defined in terms of Mellin-Barnes integral as

$$G_{p,q}^{m,n} \left( z \left| \begin{matrix} a_1, \dots, a_p \\ b_1, \dots, b_p \end{matrix} \right. \right) = \frac{1}{2\pi i} \int_c \frac{\prod_{j=1}^m \Gamma(b_j - s) \prod_{j=1}^n \Gamma(1 - a_j + s)}{\prod_{j=m+1}^q \Gamma(1 - b_j - s) \prod_{j=n+1}^p \Gamma(a_j - s)} z^j ds,$$

where  $0 \leq m \leq q, 0 \leq n \leq p$  and  $a_j, b_j$  are such the poles of  $\Gamma(b_j - s), j = \overline{1, m}$  do not coincide with those of  $\Gamma(1 - a_j - s), j = \overline{1, n}$  i.e.  $a_k - b_j \notin \mathbb{N}$  while  $z \neq 0$ .  $c$  is a suitable

integration contour which start at  $c^-i\infty$  and goes to  $c^+i\infty$  and separate the poles  $\Gamma(b_j - s), j = \overline{1, m}$  which lie to the right of the contour, from all poles of  $\Gamma(1 - a_j - s), j = \overline{1, n}$  which lie to the left of  $C$ .

The integral converges if  $\delta = m + n - \frac{1}{2}(p + q) > 0$  and  $|\arg(z)| < \delta\pi$ , see (Luke, 1969 p. 143) and Meijer (1946).

The Mathematica code for the G-function reads

$$\text{MeijerG}\left[\left\{\left\{a_1, \dots, a_n\right\}\left\{a_{n+1}, \dots, a_p\right\}\left\{b_1, \dots, b_m\right\}\left\{b_{m+1}, \dots, b_q\right\}\right\}, z\right].$$

The structure of the density function (1) can be motivated as follow:

- The integral involving the function  ${}_1F_1$  may be evaluated as a Laplace transform by making use of inverse Mellin transform technique. The proposed distribution may provide a more realistic model in connection with certain physical problems, as its density function includes a confluent hypergeometric function.
- The density function (1) provides more flexible distributions than the generalized inverse Gaussian and many other exponentiated type distributions.

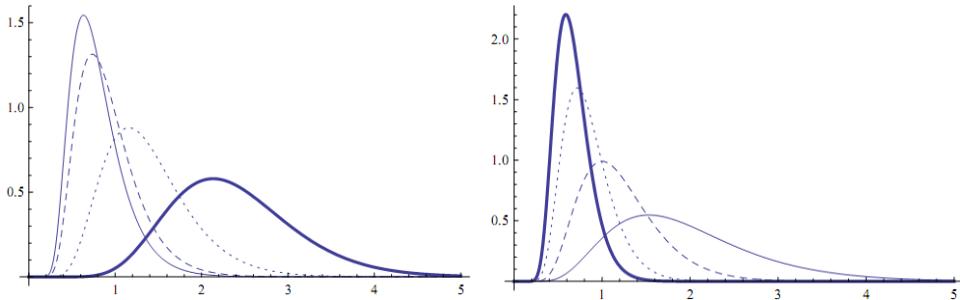


Fig. 1: The confluent hypergeometric generalized inverse Gaussian pdf.

Left panel:  $\lambda = 1.9$ ,  $b = 2.3$ ,  $\alpha = 10.1$ ,  $p_1 = 2$ ,  $p_2 = 3$  and  $m = 1.1$  (solid line),  $m = 2.1$  (dashed line),  $m = 5.1$  (dotted line),  $m = 10.1$  (thick line).

Right panel:  $\lambda = 1.9$ ,  $b = 2.3$ ,  $\alpha = 10.1$ ,  $p_2 = 3$ ,  $m = 4.1$  and  $p_1 = 2$  (solid line),  $p_1 = 4$  (dashed line),  $p_1 = 7$  (dotted line),  $p_1 = 10$  (thick line).

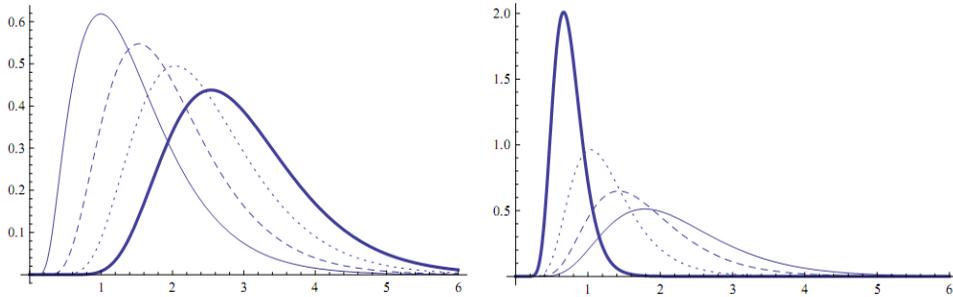


Fig. 2: The confluent hypergeometric generalized inverse Gaussian pdf.

Left panel:  $\lambda = 1.9$ ,  $b = 2.3$ ,  $\alpha = 10.1$ ,  $p_1 = 2$ ,  $m = 4.1$  and  $p_2 = 1$  (solid line),  $p_2 = 3$  (dashed line),  $p_2 = 6$  (dotted line),  $p_2 = 10$  (thick line).

Right panel:  $b = 12.3$ ,  $\alpha = 10.1$ ,  $p_1 = 2$ ,  $p_2 = 3$ ,  $m = 4.1$  and  $\lambda = 1.9$  (solid line),  $\lambda = 3.9$  (dashed line),  $\lambda = 6.9$  (dotted line),  $\lambda = 11.9$  (thick line).

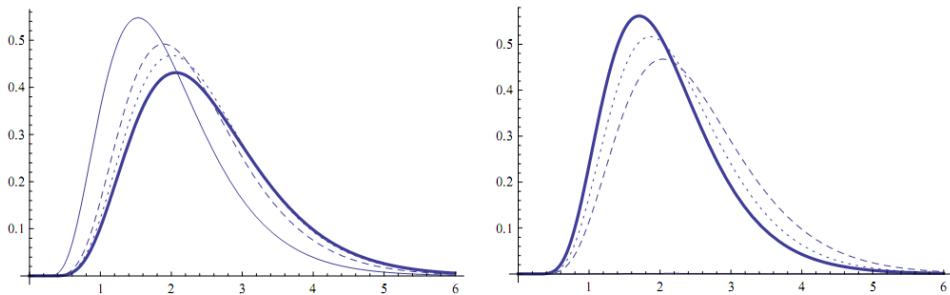


Fig. 3: The confluent hypergeometric generalized inverse Gaussian pdf.

Left panel:  $\lambda = 1.9$ ,  $\alpha = 10.1$ ,  $p_1 = 2$ ,  $m = 4.1$ ,  $p_2 = 3$  and  $b = 2.3$  (solid line),  $b = 22.3$  (dashed line),  $b = 47.3$  (dotted line),  $b = 72.3$  (thick line).

Right panel:  $\lambda = 1.9$ ,  $b = 2.3$ ,  $p_1 = 2$ ,  $p_2 = 3$ ,  $m = 4.1$  and  $\alpha = 0.1$  (solid line),  $\alpha = 0.3$  (dashed line),  $\alpha = 0.7$  (dotted line),  $\alpha = 1.2$  (thick line).

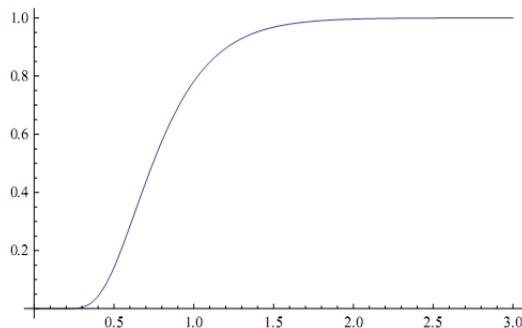


Fig. 4: The confluent hypergeometric generalized inverse Gaussian cdf for  $\lambda = 1.9$ ,  $b = 2.3$ ,  $p_1 = 4$ ,  $m = 1.1$ ,  $p_2 = 3$  and  $\alpha = 10.1$ .

The corresponding cumulative distribution function (c.d.f),  $F(x)$  and survival function,  $S(x)$ , are given by

$$F(x) = C \int_0^x t^{m-1} \exp(-p_1 t - p_2 t^{-1}) {}_1F_1(\lambda; b; -\alpha t) dt = \frac{\Gamma^{(\Theta)}\left(\begin{matrix} x \\ 0 \end{matrix}\right)(m)}{\Gamma^{(\Theta)}(m)} \quad (3)$$

and

$$S(x) = \frac{\Gamma^{(\Theta)}\left(\begin{matrix} x \\ 0 \end{matrix}\right)(m)}{\Gamma^{(\Theta)}(m)}. \quad (4)$$

Since  $f(x) > 0$ ,  $\lim_{x \rightarrow 0} f(x) = \lim_{x \rightarrow \infty} f(x) = 0$  and  $\int_0^{\infty} f(x) dx = 1$ ,  $f(x)$  is a bone fide probability function.

The left and right panels of Figure 1, 2 and 3 illustrate how the parameters  $m$ ,  $p_1$ ,  $p_2$ ,  $\lambda, b$  and  $\alpha$  affect the CHGIG distribution. The curves tend to flatten as  $m$  increases or as  $p_1$  and  $\lambda$  decreases when keeping the other parameters fixed. The left panel of Figure 2 illustrates that the parameter  $p_2$  acts somewhat as a location parameter. Figure 4 shows the cdf of the CHGIG distribution for a given set of parameters.

### 2.1 Statistical Functions

Closed form representations of the moment generating function of a CHGIG random variable which will be denoted by  $X$ , as well as the associated moments, hazard rate, mean residual life function are provided in this section. The resulting expressions can be evaluated exactly or numerically with symbolic computational packages such as *Mathematica*, *MATLAB* or *Maple*. In numerical applications, infinite sums can be truncated whenever convergence is observed.

- The moment generating function associated with the density function (1), that is

$$\begin{aligned} M_X(t) &= C \int_0^{\infty} e^{tx} t^{m-1} \exp(-p_1 t - p_2 t^{-1}) {}_1F_1(\lambda; b; -\alpha t) dt, \\ &= C \int_0^{\infty} t^{m-1} \exp(-(p_1 - t)x - p_2 t^{-1}) {}_1F_1(\lambda; b; -\alpha t) dt, \end{aligned} \quad (5)$$

where  $(p_1 - t) > 0$ ,  $p_2 > 0$  and  $b \neq 0, -1, -2, \dots$ , can be derived as follows.

Let

$$\begin{aligned} &\int_0^{\infty} t^{m-1} \exp(-(p_1 - t)x - p_2 t^{-1}) {}_1F_1(\lambda; b; -\alpha t) dt \\ &= \frac{\Gamma(b)}{\Gamma(\lambda)} \int_0^{\infty} t^{m-1} \exp(-(p_1 - t)x - p_2 t^{-1}) \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \frac{(\alpha t)^s \Gamma(-s) \Gamma(\lambda + s)}{\Gamma(b + s)} ds dt \end{aligned} \quad (6)$$

$$\begin{aligned}
&= \frac{\Gamma(b)}{\Gamma(\lambda)} 2 \left( \frac{p_2}{(p_1-t)} \right)^{m/2} \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \left( \frac{\sqrt{p_2}}{\sqrt{p_1-t}\alpha} \right)^{-s} \frac{\Gamma(-s)\Gamma(\lambda+s)}{\Gamma(b+s)} \\
&\quad \times k_{m+s} \left( 2\sqrt{(p_1-t)p_2} \right) ds, \tag{7}
\end{aligned}$$

where  $k_\nu$  is the Macdonald function (Gradshteyn and Ryzhik, 1994), defined by

$$k_\nu = \pi/2 \frac{I_{-\nu}(z)I_\nu(z)}{\sin \nu\pi}.$$

$I_\nu(z)$  denoting the modified Bessel function of the first kind (Abramowitz and Stegun, 1972), given by

$$I_\nu(z) = \sum_{n=0}^{\infty} \frac{(z/2)^{\nu+2n}}{n!\Gamma(\nu+n+1)}.$$

Making use of the extended gamma function (Chaudhry and Zubair, 2001), the modified Bessel function of first kind kind (Abramowitz and Stegun, 1972) and the residue theorem (Ahlfors, 1966) and (7), one has

$$\begin{aligned}
M_X(t) &= \frac{\Gamma(b)}{\Gamma^{(\Theta)}(m)\Gamma(\lambda)} \sum_{n=1}^{\infty} \frac{\left( (p_1-t)p_2 \right)^n}{n!} \left( (p_1-t)^{-m} G_{3,3}^{2,2} \left( \alpha/p_1 \middle| \begin{matrix} 1, m, b \\ \lambda, m, m-n \end{matrix} \right) \right. \\
&\quad \left. - p_2^m G_{2,4}^{2,2} \left( 1/p_2 \alpha \middle| \begin{matrix} 1, m, b, m+n+1 \\ \lambda, m \end{matrix} \right) \right), \tag{8}
\end{aligned}$$

which can be expressed as

$$\begin{aligned}
M_X(t) &= \frac{\Gamma(b)}{\Gamma^{(\Theta)}(m)\Gamma(\lambda)} \sum_{n=1}^{\infty} \frac{\left( (p_1-t)p_2 \right)^n}{n!} \left( (p_1-t)^{-m} \right. \\
&\quad \left. \times G_{3,3}^{2,2} \left( \alpha/(p_1-t) \middle| \begin{matrix} 1-m, 1-\lambda, -m+n+1 \\ 0, 1-m, 1-b, -m-n \end{matrix} \right) \right) \\
&\quad \left. - p_2^m G_{2,4}^{2,2} \left( p_2 \alpha \middle| \begin{matrix} 1-m, 1-\lambda \\ 0, 1-m, 1-b, -m-n \end{matrix} \right) \right),
\end{aligned}$$

where  $(p_1-t) > 0$ ,  $p_2 > 0$  and  $b, \lambda, m \neq 0, -1, -2, \dots$

- The mean and variance of the distribution of  $X$  are given by

$$E(X) = \frac{\Gamma^{(\Theta)}(m+1)}{\Gamma^{(\Theta)}(m)} \tag{9}$$

and

$$V(X) = \frac{1}{\Gamma^{(\Theta)}(m)} \left( \Gamma^{(\Theta)}(m+2) - \frac{(\Gamma^{(\Theta)}(m+1))^2}{\Gamma^{(\Theta)}(m)} \right). \tag{10}$$

The information function is simply the inverse of the variance.

- The factorial moments for the probability density function defined in (1) are as follows

$$\begin{aligned} E(X(X-1)(X-2)\dots(X-\gamma+1)) &= \sum_{j=1}^{\gamma-1} \varphi_j (-1)^j E(X^{\gamma-j}) \\ &= \sum_{j=1}^{\gamma-1} \varphi_j (-1)^j \frac{\Gamma^{(\Theta)}(m+\gamma+1)}{\Gamma^{(\Theta)}(m)}, \end{aligned} \tag{11}$$

where the  $\varphi_j$ 's are non-null real numbers that satisfy the first identity.

- The  $i^{th}$  order negative moment is

$$E(X^{-i}) = \sum_{j=1}^{\gamma-1} \frac{\Gamma^{(\Theta)}(m-i)}{\Gamma^{(\Theta)}(m)} E, \quad \Re(m-1) > 0. \tag{12}$$

- The hazard rate function (failure rate) which is defined as

$$Z(x) = \frac{f(x)}{S(x)},$$

where  $f(x)$  and  $S(x)$  are given in (1) and (4), has its origin in reliability theory.

In this case,

$$Z(x) = \frac{x^{m-1} e^{-p_1 x - p_2 x^{-1}} {}_1F_1(\lambda; b; -\alpha x)}{\Gamma^{(\Theta)}\left(\begin{matrix} \infty \\ x \end{matrix}\right)(m)}. \tag{13}$$

- The mean residue life function is defined as

$$K(x) = \frac{1}{S(x)} \int_x^\infty (y-x)f(y)dy = \frac{1}{S(x)} \int_x^\infty y f(y)dy - x = \frac{1}{S(x)} \left[ E(Y) - \int_0^x y f(y)dy \right] - x,$$

where  $f(y)$ ,  $S(x)$  and  $E(Y)$  is given in (1), (4) and (9) respectively.

Accordingly,

$$K(x) = \frac{1}{S(x)} \left[ E(Y) - \frac{\Gamma^{(\Theta)}(m+1)}{\Gamma^{(\Theta)}(m)} dy \right] - x. \tag{14}$$

### 3. APPLICATION

In this section, we will use the two parameter gamma, ESGamma (Nadarajah and Kotz, 2006), generalized gamma (GG) (Agarwal and Kalla, 1996; Nadarajah, 2008), the

generalized inverse Gaussian (GIG) and the confluent hypergeometric generalized inverse Gaussian (CHGIG) distributions to model the well-known ‘Ball bearings’ data set. The maximum likelihood approach will be utilized to estimate the parameters. Additionally, two goodness-of-fit measures are defined and employed to compare the density estimates.

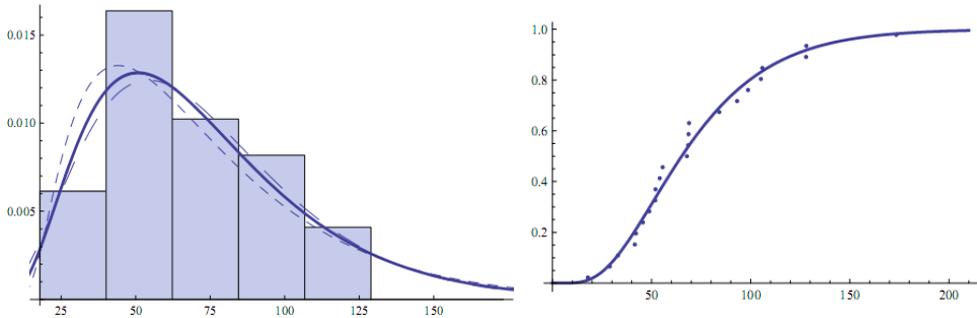


Fig. 5: Left panel: The graphs of gamma (dotted line), ESGamma (small dashes), GG (long dashes), GIG (dolid line) and CHGIG (thick line) density estimates superimposed on the histogram for ball bearings data.  
Right panel: The CHGIG cdf estimates and empirical cdf.

### 3.1 Maximum Likelihood Estimation

In order to estimate the parameters of the proposed confluent hypergeometric generalized inverse Gaussian distribution as specified by the density function appearing in Equation (1), the loglikelihood of the sample is maximized with respect to the parameters by making use of the *NMaximize* command in the symbolic computational package *Mathematica*. Given the data  $x_i, i=1,2,\dots,n$  the loglikelihood function is given by

$$l(\Theta) = -n \log(\Gamma^\Theta(m)) + (m-1) \sum_{i=0}^n \log(x_i) - p_1 \sum_{i=0}^n x_i - p_2 \sum_{i=0}^n x_i^{-1} + \sum_{i=0}^n \log({}_1F_1(\lambda; b, -\alpha x_i)), \quad (15)$$

where  $f(x)$  is as given in (1).

### 3.2 Goodness-of-Fit Statistics

The Anderson-Darling and the Cramér-von Mises statistics are widely utilized to determine how closely a specific distribution whose associated cumulative distribution function denoted by  $\text{cdf}(\cdot)$  fits the empirical distribution associated with a given data set. The smaller these statistics are, the better the fit. Upper tail percentiles of the asymptotic distributions of these goodness-of-fit statistics were tabulated in Stephens (1976).

**Table 1**  
**Estimates of Parameters and Goodness-of-Fit Statistics**  
**for the Ball Bearings Data under Various Distributions**

Estimates	Gamma	ESGamma	GG	GIG	GHGIG
$\hat{m}$	4.02802	22.131	4.03031	2.51277	6.45952
$\hat{p}_1$	0.0557669	--	0.0557399	0.0441474	0.0441129
$\hat{p}_2$	--	--	--	37.2274	3.11946
$\hat{\beta}$	--	0.0335813	--	--	--
$\hat{\lambda}$	--	--	0.0040165	--	3.88653
$\hat{b}$	--	--	--	--	6.49732
$\hat{z}$	--	--	0.00100415	--	--
$\hat{\alpha}$	--	--	--	--	0.260609
$A_0^2$	0.215968	0.227772	0.215878	0.190673	0.189267
$W_0^2$	0.0392492	0.0348883	0.03924	0.0325841	0.0324115

The confluent hypergeometric generalized inverse Gaussian model was applied to a data set published in (Lawless, 1982, p. 228), which consists of the number of million revolutions before failure for each of 23 ball bearings in a life testing experiment. The pdf and cdf estimates are plotted in Figure 5 for CHGIG distribution. The estimates of the parameters and the values of the Anderson-Darling and Cramér-von Mises goodness-of-fit statistics are given in Table 1. It is seen that the CHGIG model provides the best fit.

#### 4. CONCLUDING REMARKS

A confluent hypergeometric generalized inverse Gaussian density function has been defined and some of its properties were discussed. Certain related statistical functions have also been derived. An application of the new distribution to an actual data set was presented; it was shown that it can provide a better fit than other exponential-type models. The presented extension could be utilized to model data arising in numerous areas of scientific investigation.

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